



Coordinated Flight of Uninhabited Air Vehicles

M.S.E. Thesis of Olivier Laplace

- **Research Motivation and Problem Formulation**
- **Theory of Rule-Based Control**
- **Team Organization and UAV Cooperation**
- **UAV Flight Control System**
- **Case Study Implementation**
- **Simulation Results**
- **Conclusions and Recommendations**

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for
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Rule-Based Implementation of Nonlinear-Inverse Dynamic Flight Control

