



# **Impact of Flight Operation Uncertainties on the the Design of Advanced Noise Abatement Procedures**

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## Noise Abatement Procedures

- **Noise is an important factor in the siting and operation of airports**
  - Lengthy environmental studies and community agreement required for approval of airport expansion or airspace changes and federal mitigation funding
- **Problem is global**
  - Large international airports make significant contributions to national economies
- **Engine technology has provided significant noise reductions**
  - Higher bypass-ratio engines (designed for increased fuel consumption) generate lower noise levels for same thrust
  - Now in period of diminishing returns



## Noise Abatement Procedures (2)

- Advanced flight guidance technologies enable operational procedures that provide significant additional noise reductions
  - Thrust management strategies redistribute noise impact during departure and reduce impact during approach
  - Lateral deviations direct aircraft away from populated areas during departure and approach
  - Area Navigation (RNAV) using position information from the Global Positioning System (GPS) enables trajectories that can be adjusted for noise considerations



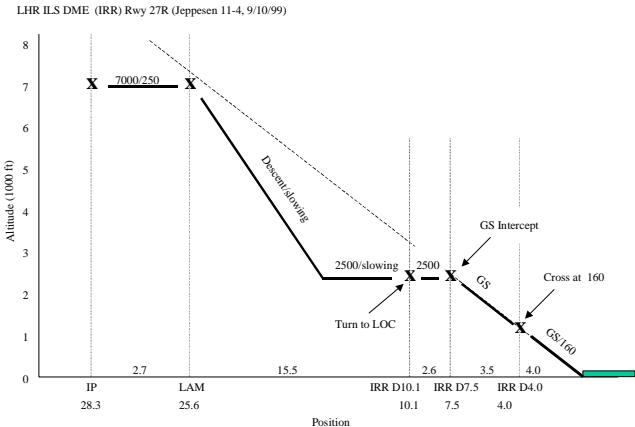
## Experimental Study : pilot-in-the-loop simulation

- **Objectives**
  - Investigate the operational acceptability and human factors issues of advanced noise abatement procedures (ANAP)
  - Examine the noise impact of each procedure
- **Method**
  - NASA Ames Research CVS RF (Crew-Vehicle Research Simulation Facility) Facility B747-400 simulator
  - Eight B747-400 airline captains and eight first officers
  - Equipage: PFD, NAV Display, FMS, MCP, AFDS, MCDU
- **Experiment Design**
  - Noise sensitive Airport : London Heathrow (LHR)
  - Arrival NAPs : Standard, CDA(Continuous Descent Approach), Two-Segment Segment Approach(TSA), Low Power/Low Drag(LPLD), LHR Runways 27L/R 27L/R
  - Departure NAPs : ICAO-A, ICAO-1000, MCG (Maximum Climb Gradient), LHR LHR Runways 9L/R

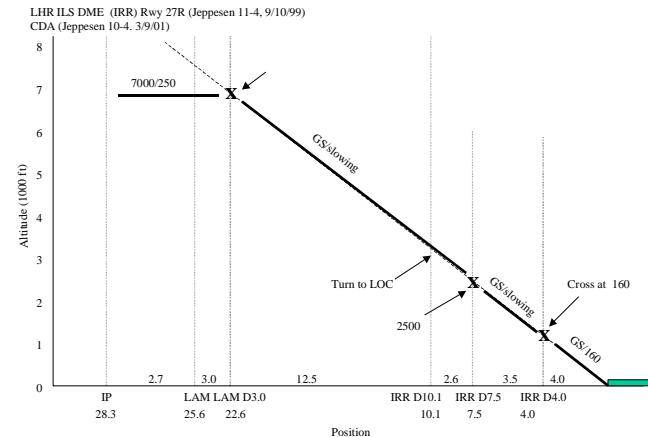


# Four Arrival NAPs

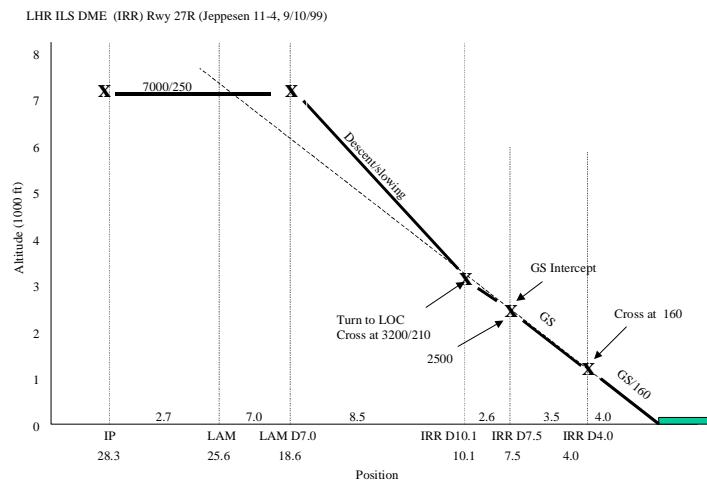
**LHR ILS DME 27R Arrival Profile - Standard**



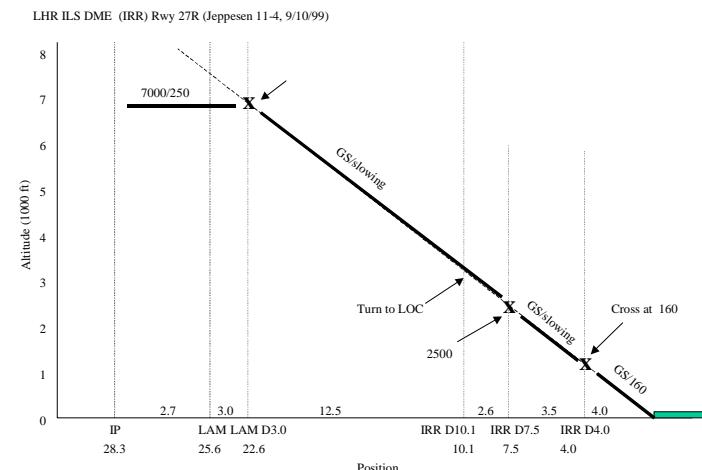
**LHR ILS DME 27R Arrival Profile - CDA**



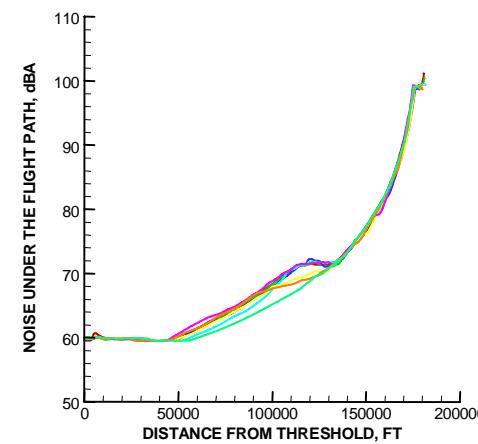
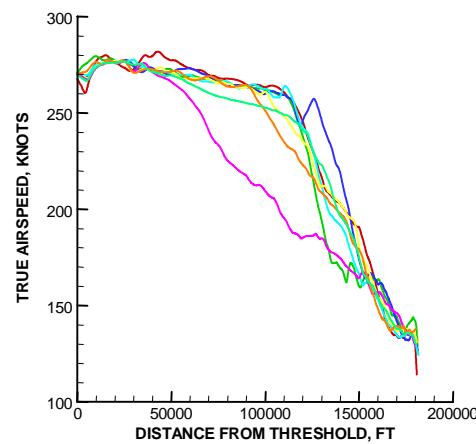
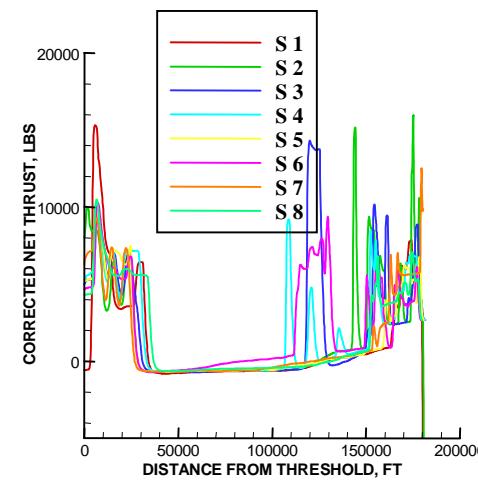
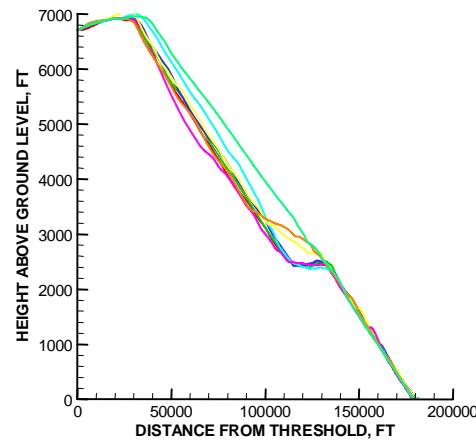
**LHR ILS DME 27R Arrival Profile - TSA**



**LHR ILS DME 27R Arrival Profile - LPLD**

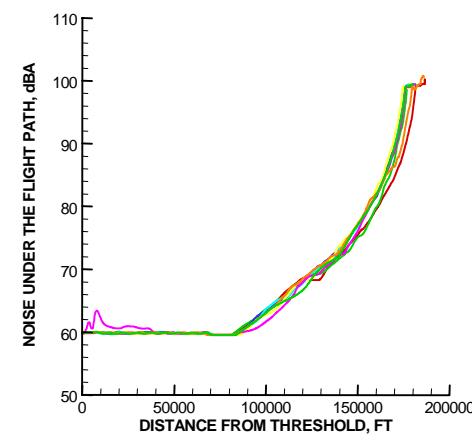
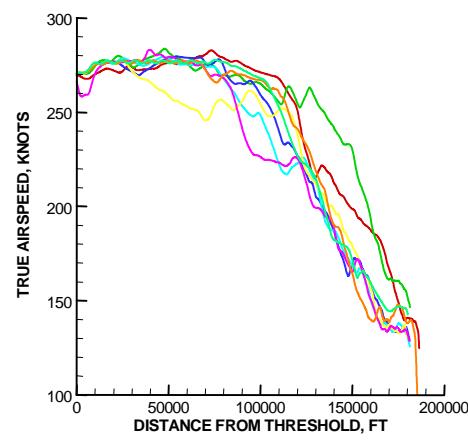
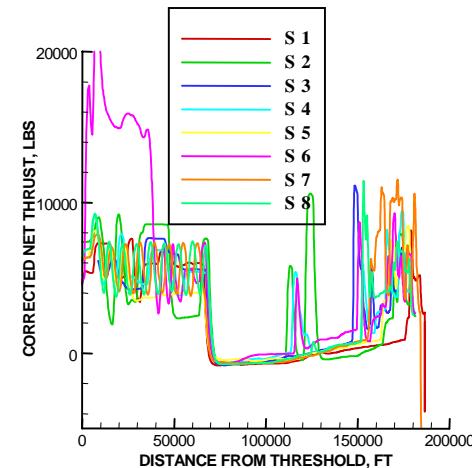
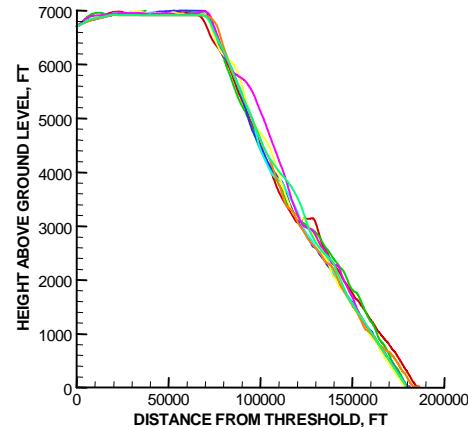


## Standard Approach in Manual Mode

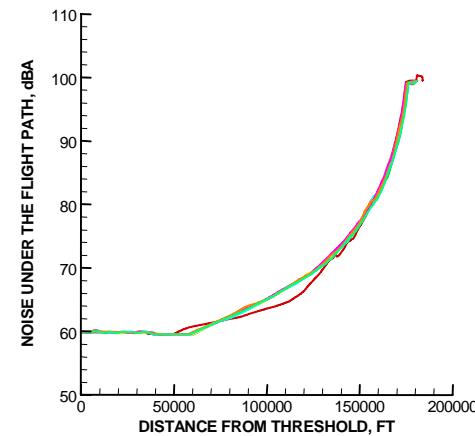
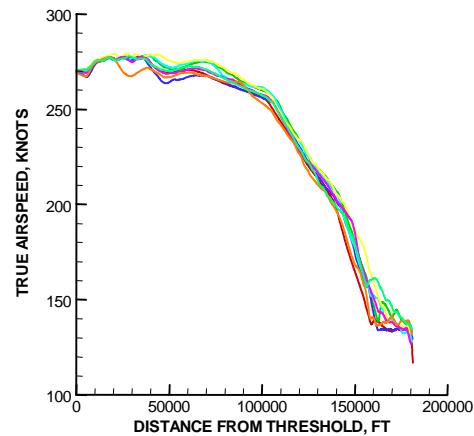
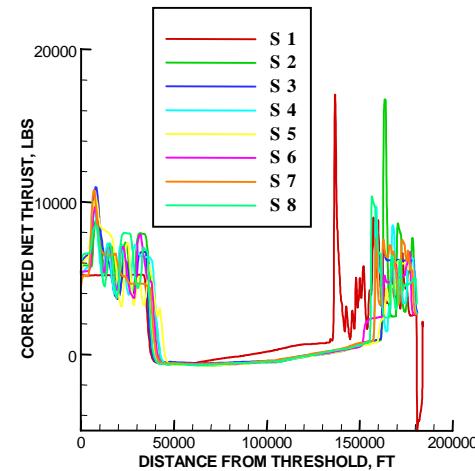
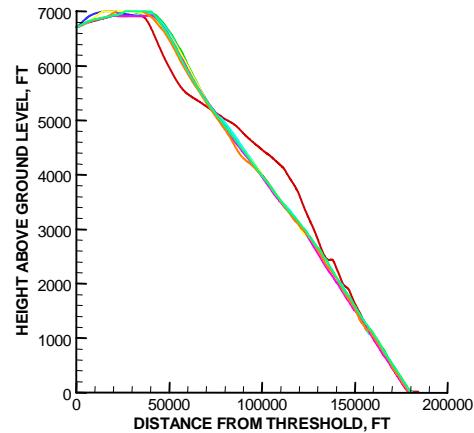




## Two Segment Approach in Manual Mode

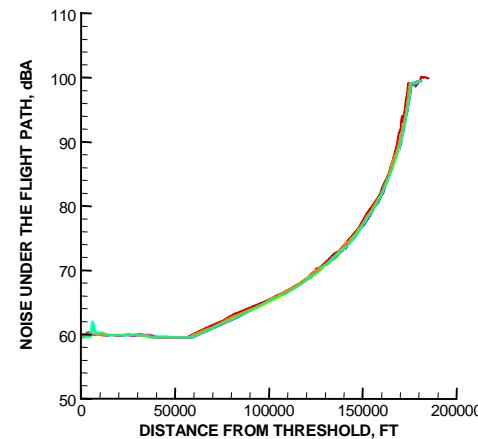
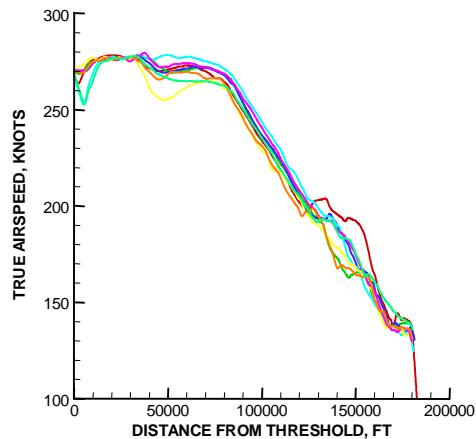
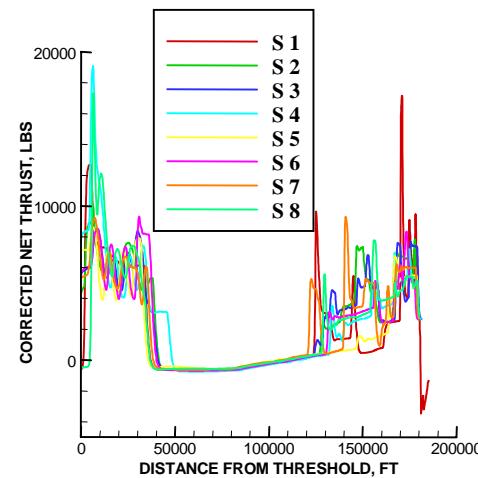
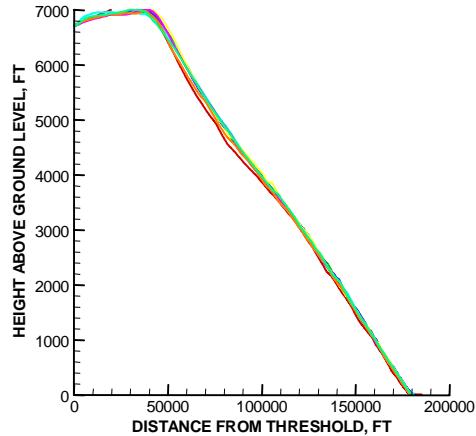


# Continuous Descent Approach in Manual Mode





## LPLD Approach in Manual Mode



# Implementation of NAPs

- Benefits of advanced approach noise abatement procedures (CDA, ACDA, LPLD, TSA) have been recognized and documented (ex: Clarke, CVSRF experiments).
- Implementation of procedures limited by air traffic control considerations
  - Difficult to predict future position of aircraft not flying at constant speed, especially in ill-defined wind field or severe weather
  - High controller workload to mix traffic while maintaining appropriate separation and sequencing
  - Procedures only implemented in low traffic environments (tested in Europe)



**Need to add automation and structure to ATC process to complement human monitoring and decision making**

- Automation decision aids and/or
- Additional rules/structure

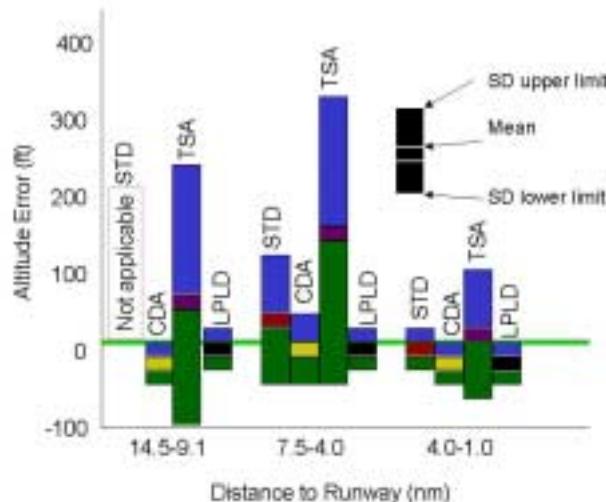
# Quantification of Operation Uncertainty (CVSRF Experimental Study)

- Pilot judgments and operational acceptability**

Rating	Definition
1	Excellent; no pilot effort required
2	Good; negligible deficiencies; pilot effort not a factor
3	Fair; mild deficiencies; minimal pilot effort required for desired performance
4	Minor deficiencies; moderate pilot effort required for desired performance
10	Impossible; unacceptable; pilot cannot complete task

Independent Variable	Questionnaire Score (Mean/SD)			
	STD	CDA	TSA	LPLD
NAP	1.85/ 0.35	2.35/ 0.72	3.41/ 0.74	2.07/ 0.34
Control Mode	AUTO	MAN		
	2.05/ 0.39	2.78/ 0.53		

- Pilot performance (auto & manual), flying accuracy**

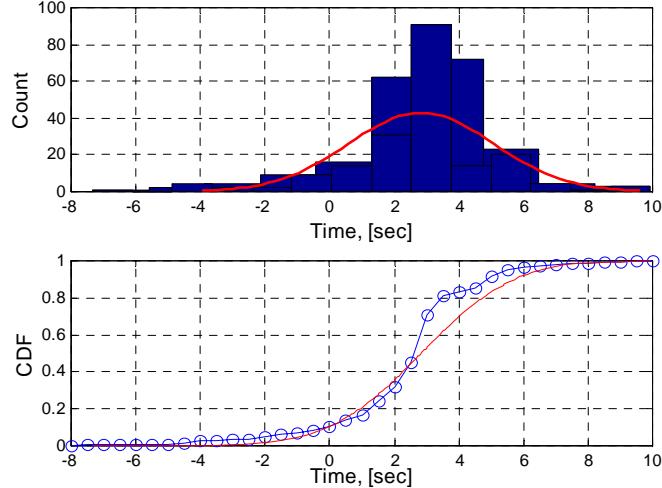


NAP	Vertical Path Deviation		Lateral Path Deviation	
	Mean Error	SD	Mean Error	SD
STD	27.0	70.3	-3.3	59.5
CDA	-14.8	5.1	-6.7	14.7
TSA	131.4	168.4	-196.8	430.9
LPLD	-7.1	10.7	19.3	19.7

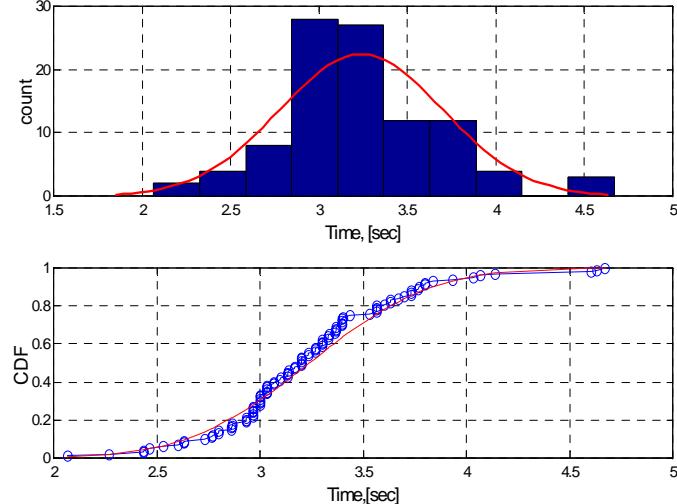
# Quantification of Operation Uncertainty

- Pilot response time (gear,flap)

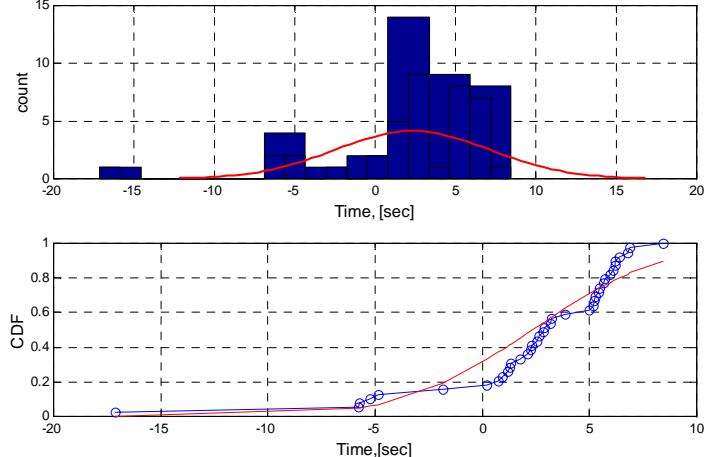
Histogram Pilot Response Time With Cues From Flying Pilot,  $m = 2.8318$ ,  $\sigma = 2.2483$



Histogram of Pilot Response Time,  $m = 3.24$ ,  $\sigma = 0.46369$

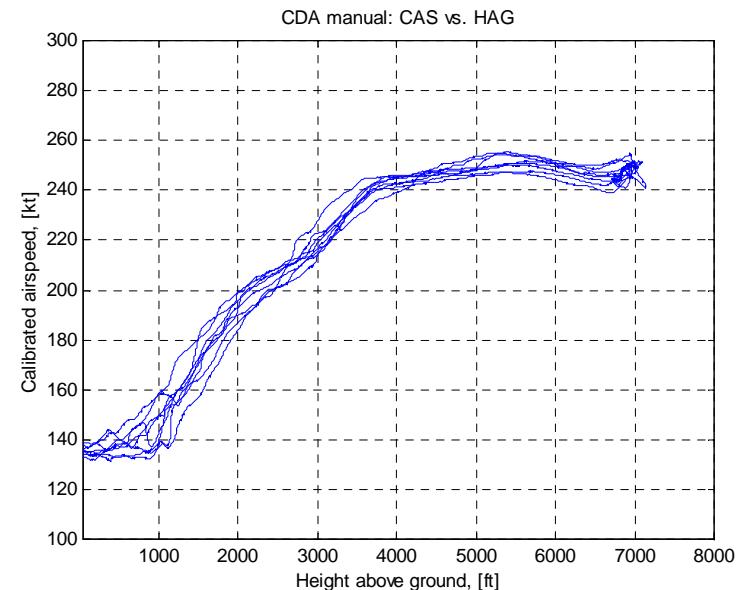
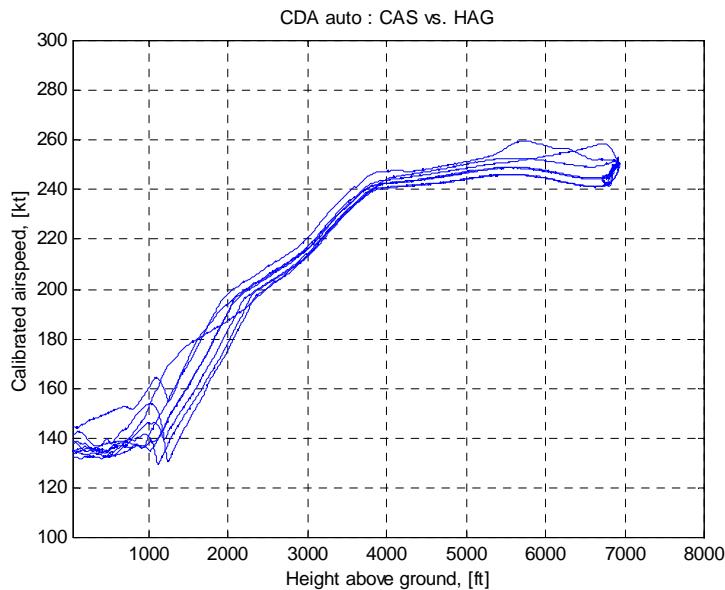


Histogram of Pilot Response Time with Turbulence,  $m = 2.322$ ,  $\sigma = 4.8129$



# Quantification of Operation Uncertainty

- **Uncertainty in aircraft's**
  - Position : limited by ASRs radar resolution ~ 150-300m
  - Velocity : influenced by order of pitching and cutting back thrust at GS intercept



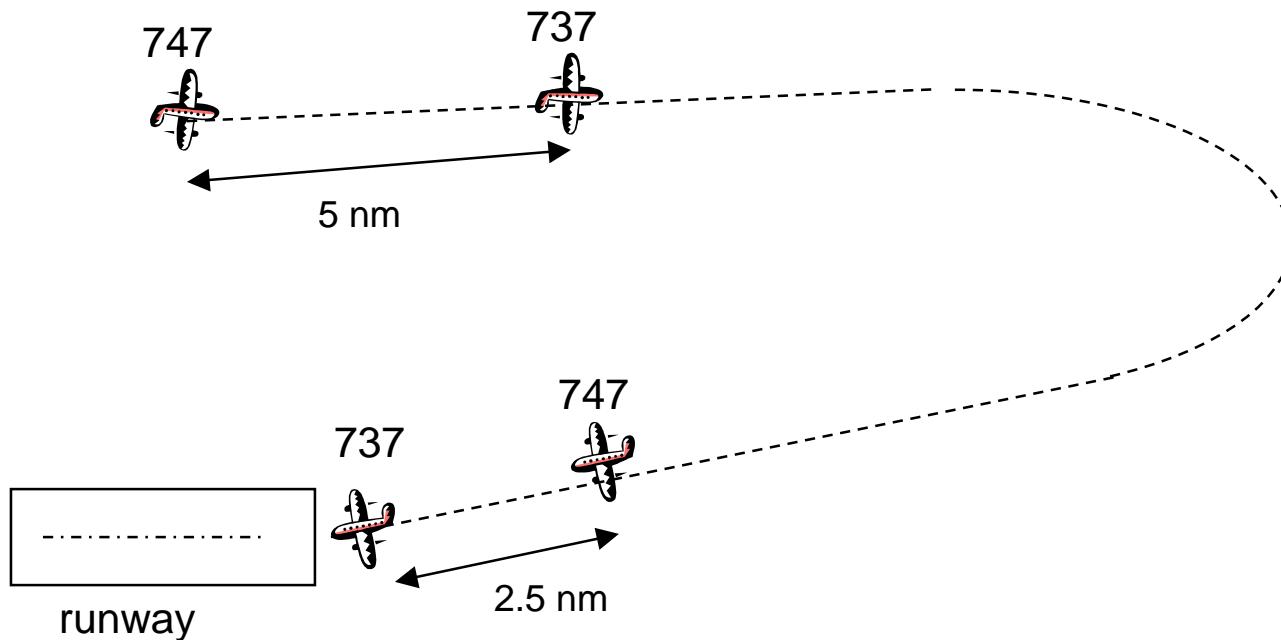


# Quantification of Operation Uncertainty

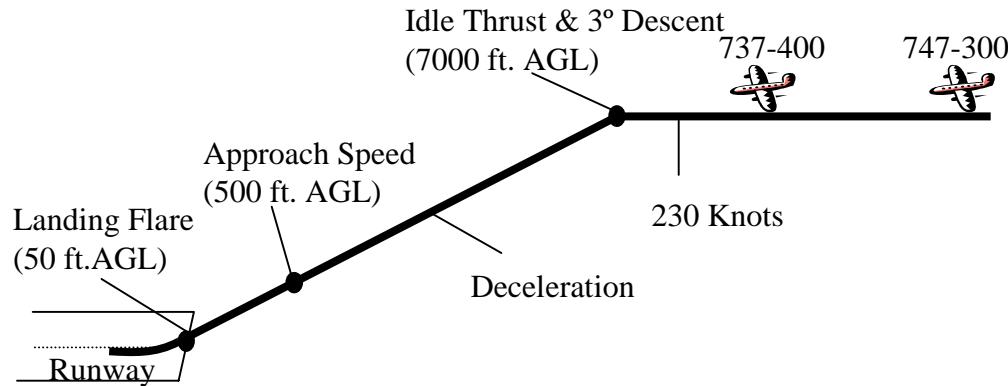
- Others :
  - Aircraft characteristics: Heavy vs. Large vs. Medium vs. Small
  - Aircraft Navigation System: FMS types (geometric vs. aircraft performance database) and capability(VNAV,FPA)

# Performance and Limitation of Automation Tools

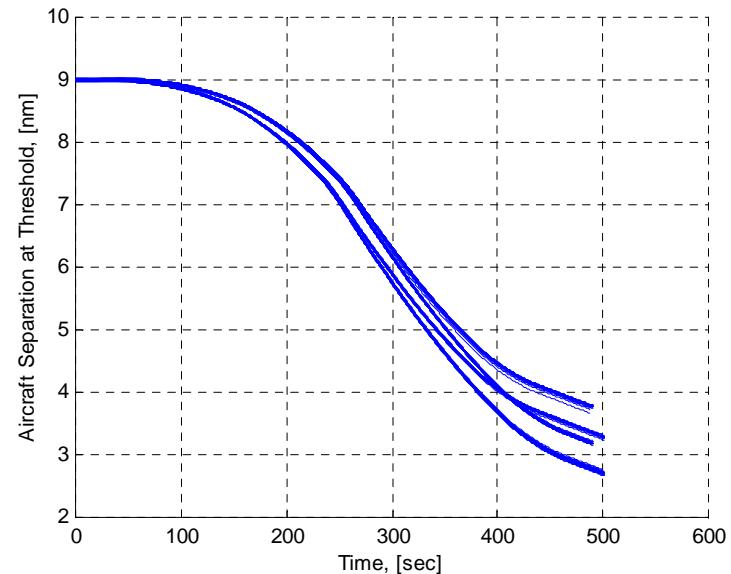
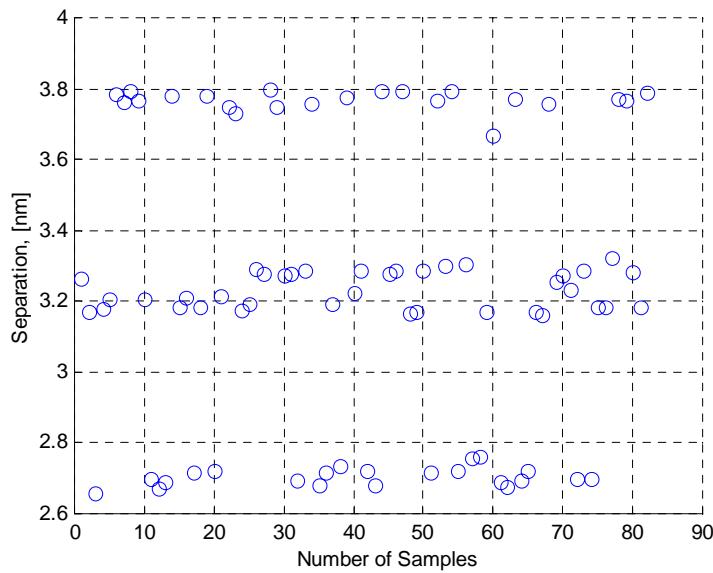
- Governed by quality and quantify of information available i.e. quality of sensors, GPS signals ...
- Established through Monte-Carlo simulations results



# Two aircraft simulation example (1)

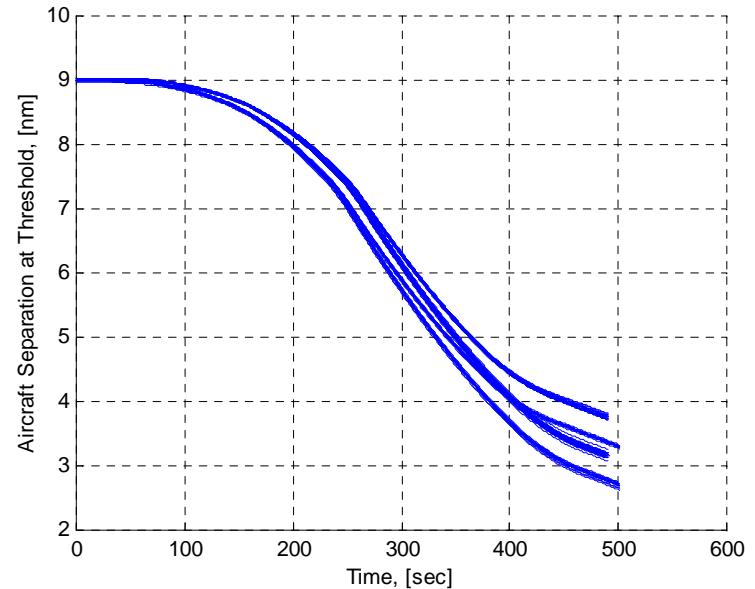
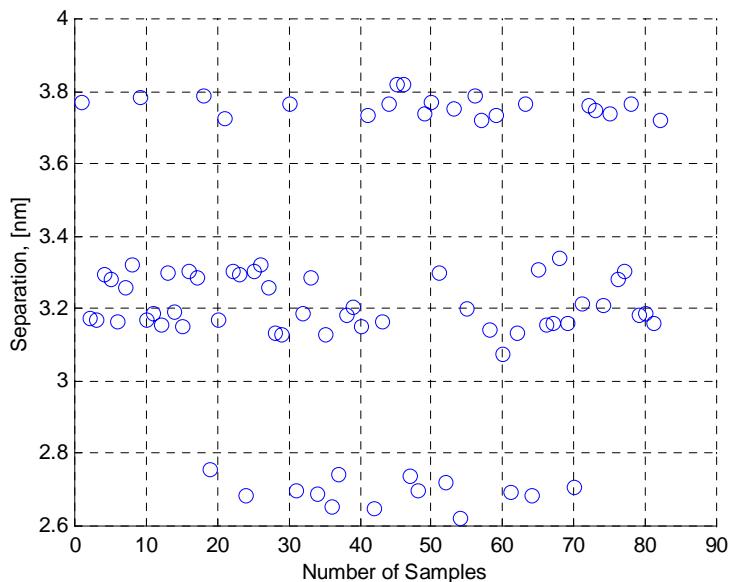


- Normal pilot response time :



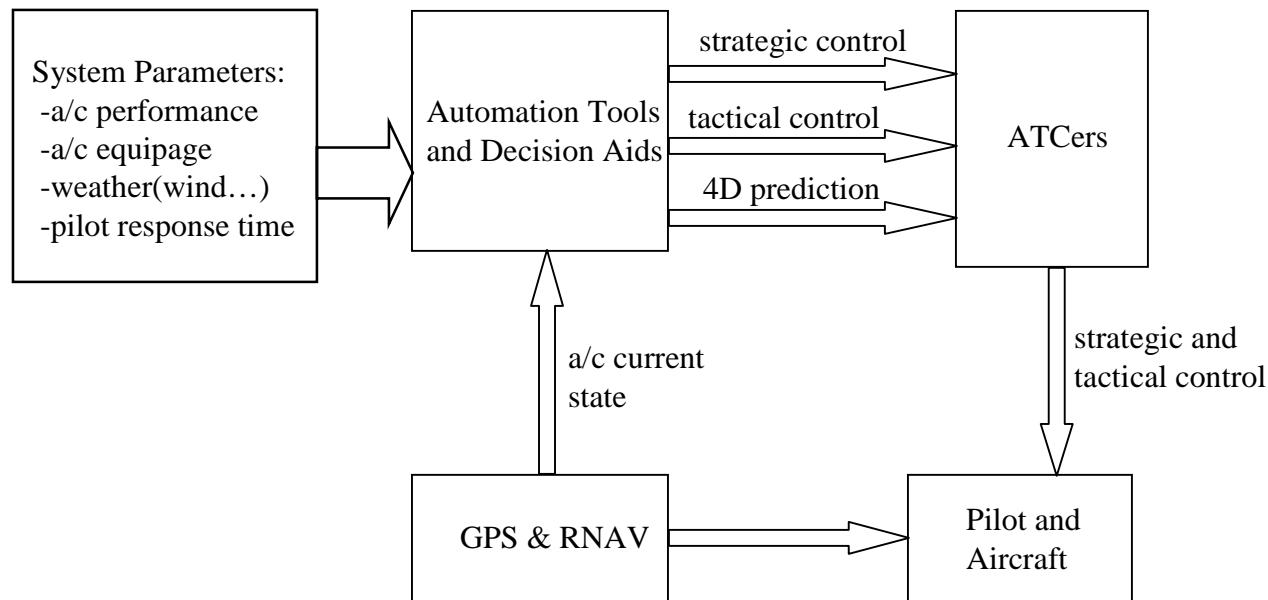
## Two aircraft simulation example (2)

- Pilot response time with turbulence



# Framework to Integrate NAPs into the ATC System

- Identify appropriate task-allocation architectures (strategic vs. vs. tactical control, air vs. ground responsibility) required to manage system complexity.
- Example of a proposed framework:

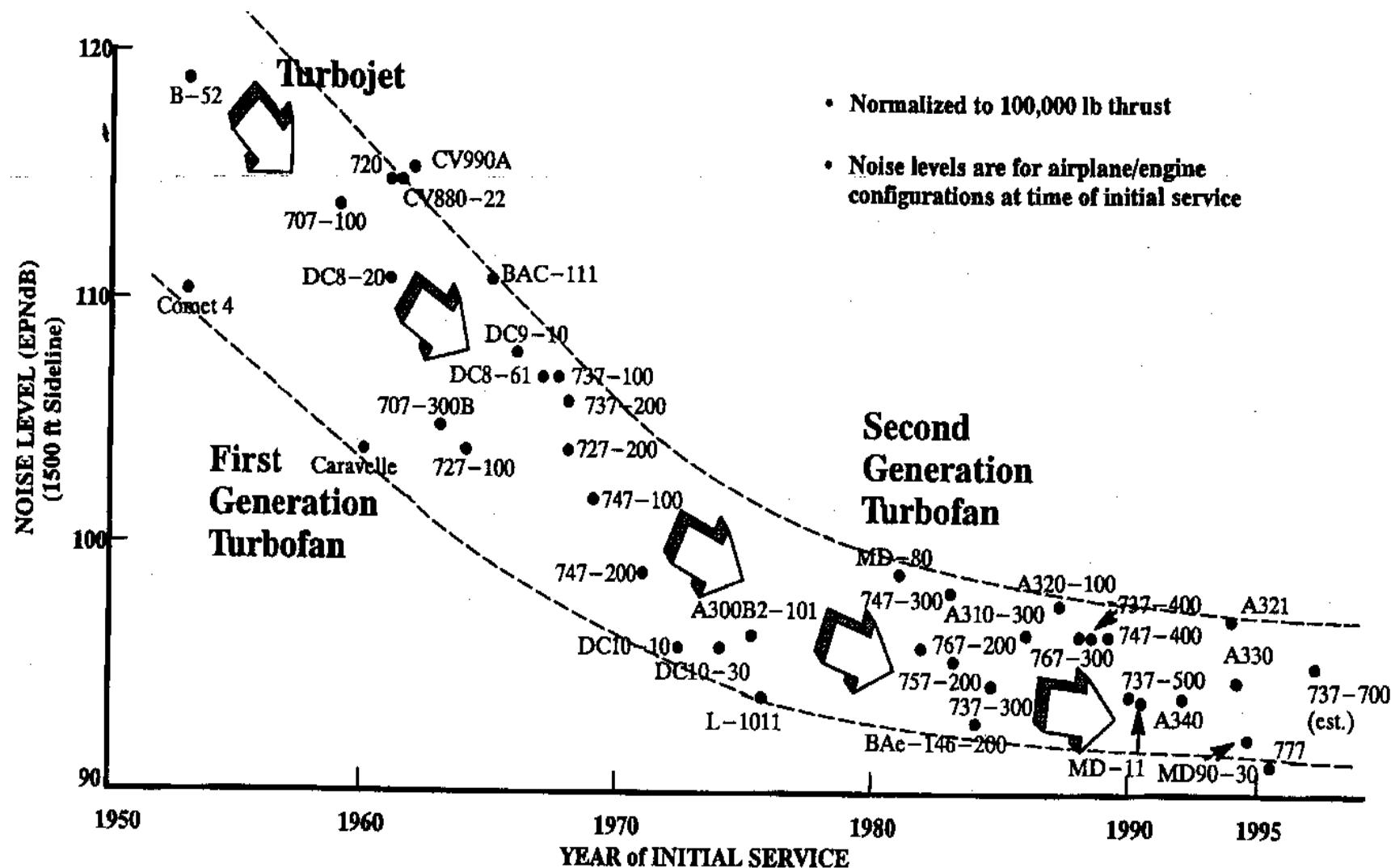




# Ongoing Research...

- **Evaluate developed NAP through simulator experiments with pilots and air traffic controllers in the loop:**
  - Incorporate system constraints, automation limitations, and proposed frameworks. Include realistic traffic, wind, VNAV FMS,....
  - Conduct experiments in an aFAST-like environment i.e. fly with aFAST advisories to optimize system's capacity, so meeting a speed target may not be required
  - Obtain air traffic controller's performance and response, and other ATC operation issues

# Aircraft Noise



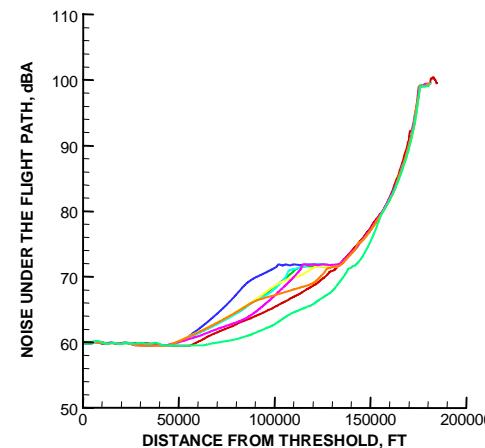
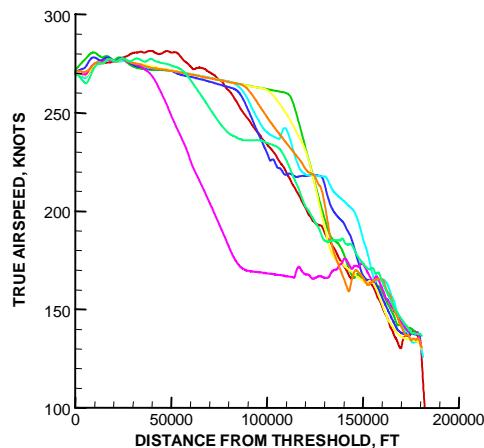
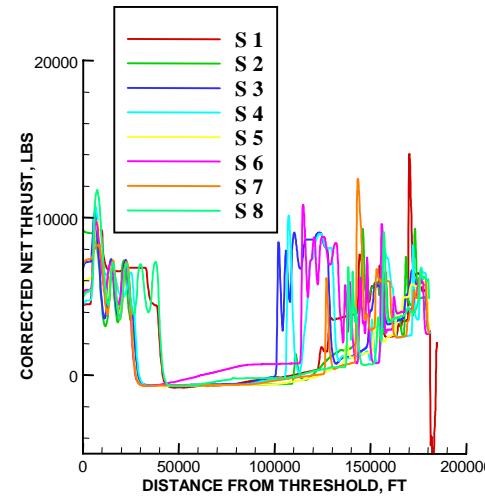
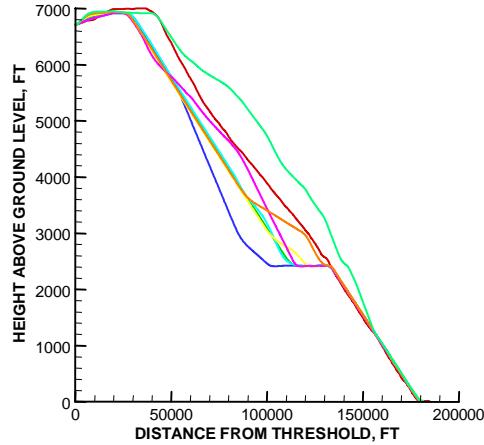
\* Courtesy of Kenneth W. Orth, The Boeing Company

## Problems with “Europe” CDAs

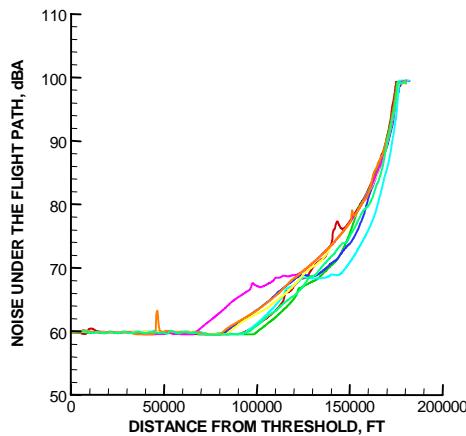
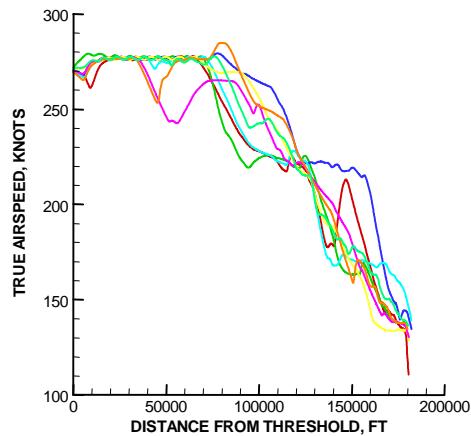
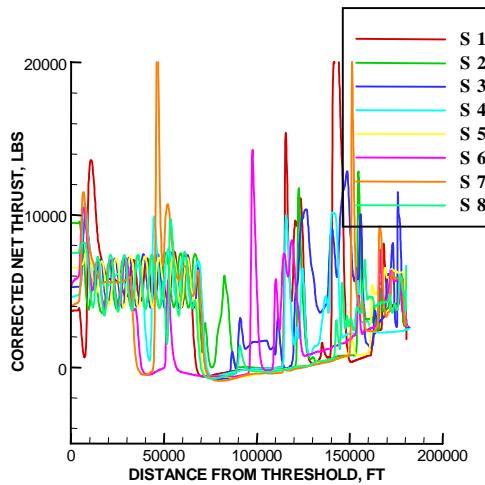
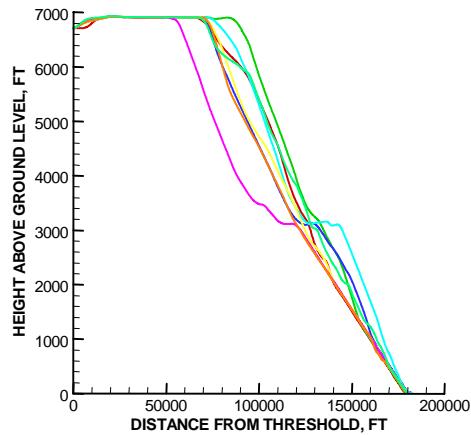
- Adopted in 6 nations
- ATC can't intervene once CDA procedures started
- Arrival time highly unpredictable:
  - Pilot do not respond uniformly to ATC instructions : banking early or causing delay because of clarification request .
  - Wind changes in direction and speed with altitude : as a/c descend (at diff. rates), effect of wind on ground track varies.
  - Aircraft turn at different rates.
  - Wind shear cause aircraft to experience rapid change in its ground ground track or speed as descending through wind shear level.



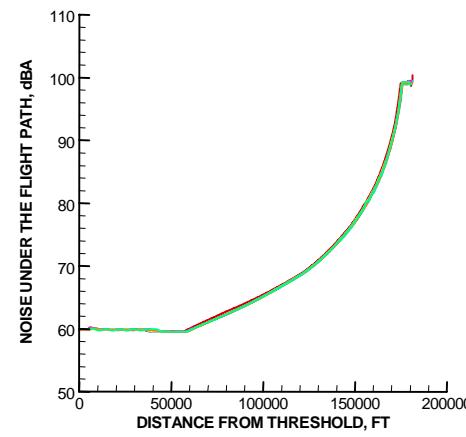
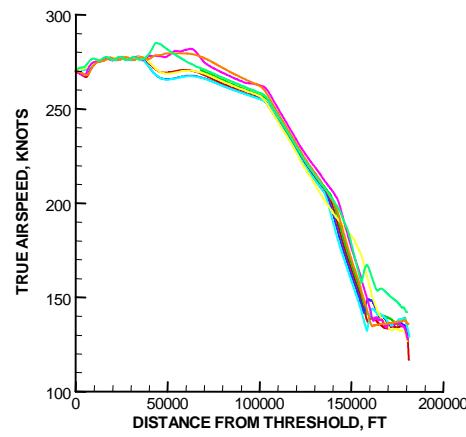
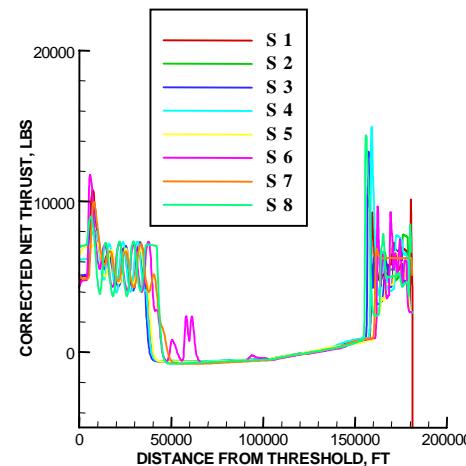
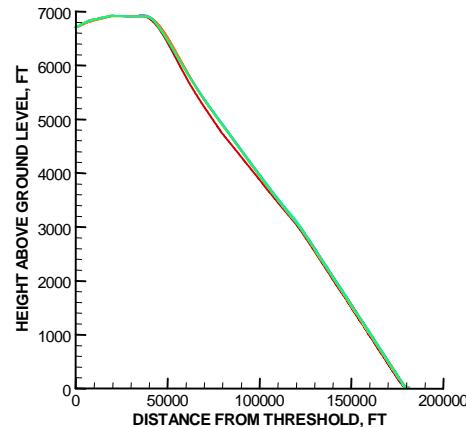
## Standard Approach in Auto Mode



## Two Segment Approach in Auto Mode



# Continuous Descent Approach in Auto Mode





## LPLD Approach in Auto Mode

